



Deep Learning-based Damage Mapping with InSAR Coherence Time Series

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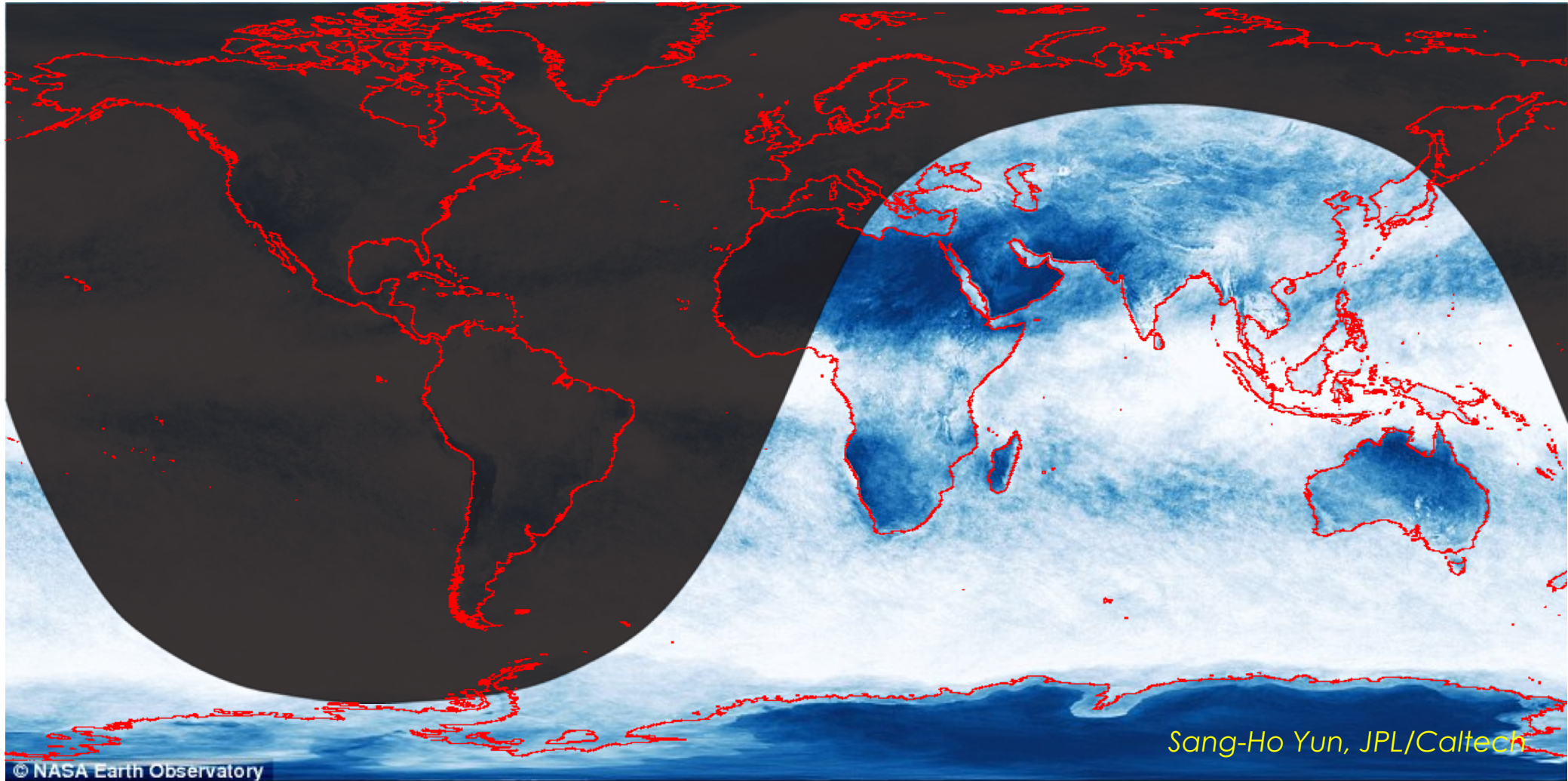
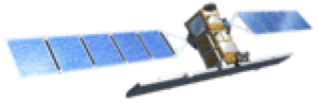
 Feedback form: <https://bit.ly/2OkRT41>

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Stephenson et al., IEEE Transactions on Geoscience and Remote Sensing (in revision)

Satellite radar data has key advantages



A 'Golden Age' of Satellite Radar

"A paradigm shift is...taking place in spaceborne SAR systems" — Alberto Moreira (2014), German Aerospace Center

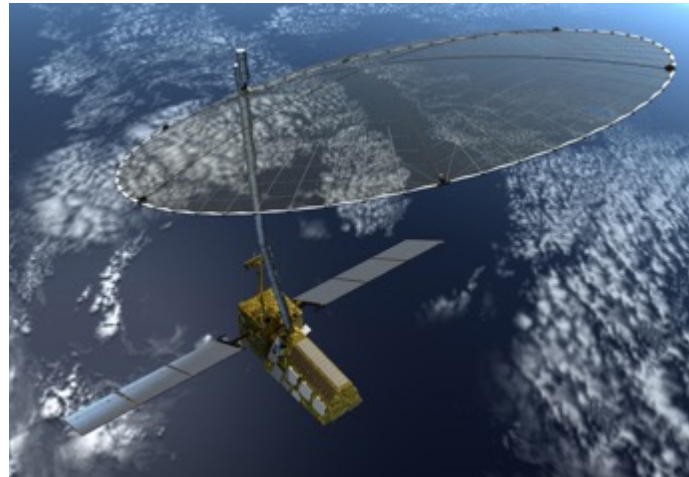
Currently acquiring data:



Sentinel 1-A/B

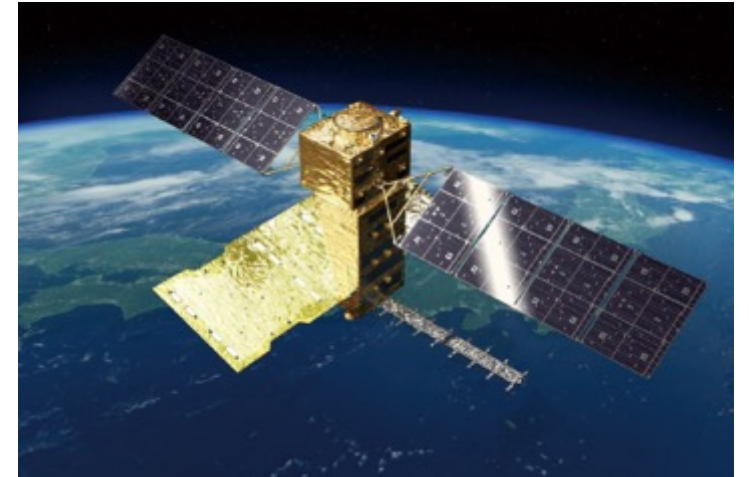
Image: ESA

Launching in the next few years:



NISAR

Image: NASA

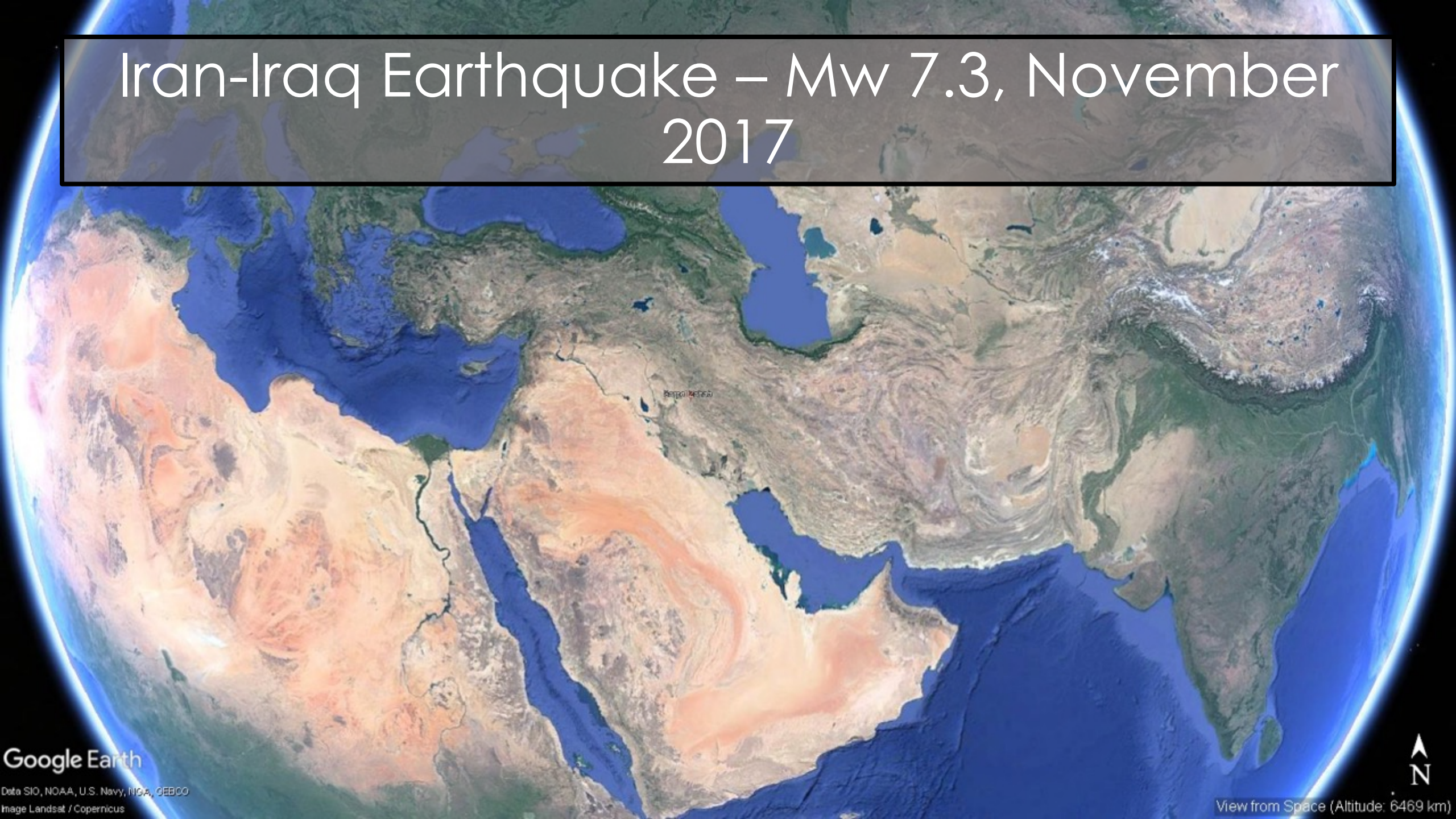


ALOS-4

Image: JAXA

How can we apply *machine learning* to large quantities of *satellite based radar* data to rapidly and reliably *map damage* in the event of major disasters?

Iran-Iraq Earthquake – Mw 7.3, November 2017



Google Earth

Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Image Landsat / Copernicus

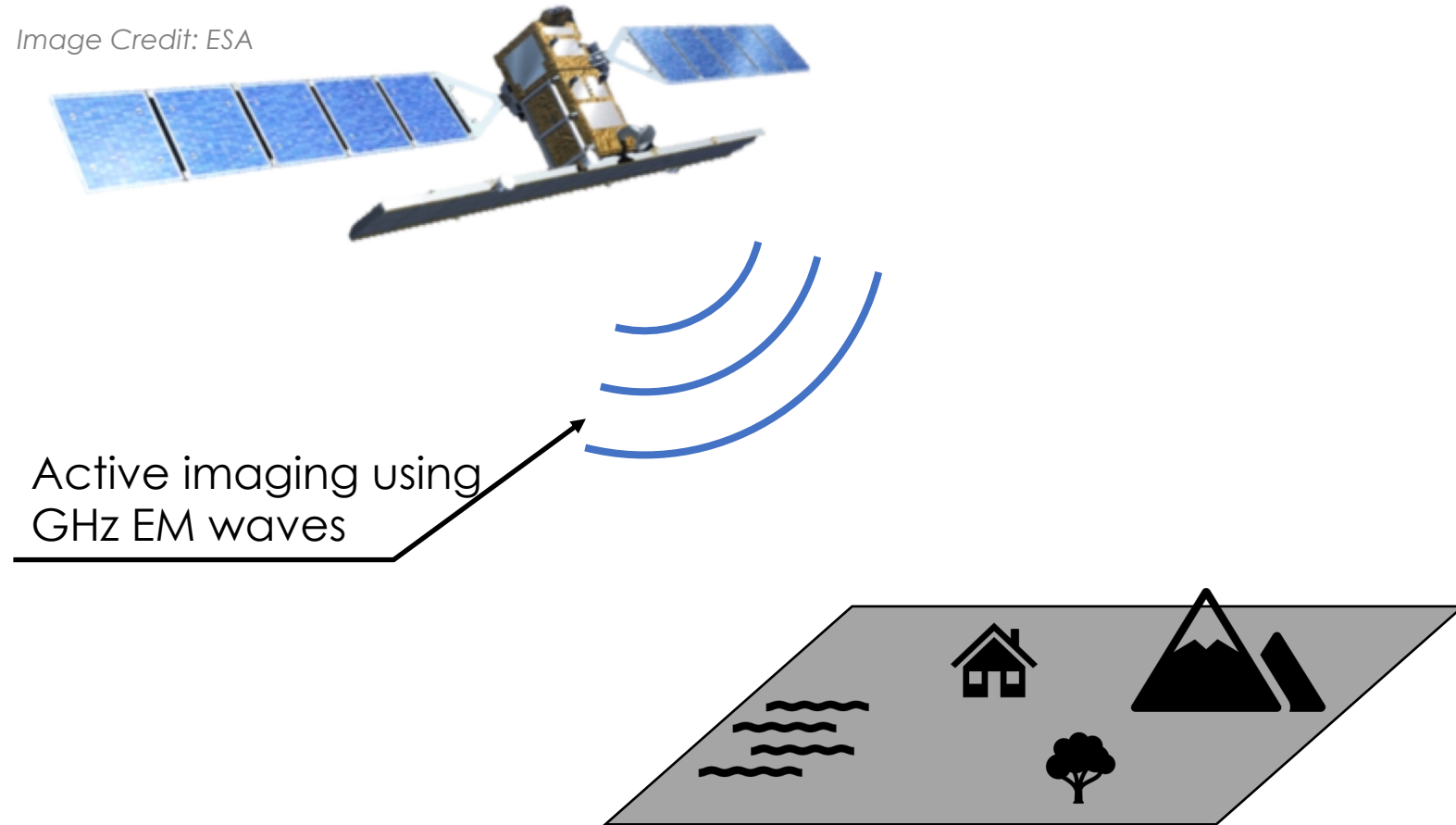


View from Space (Altitude: 6469 km)

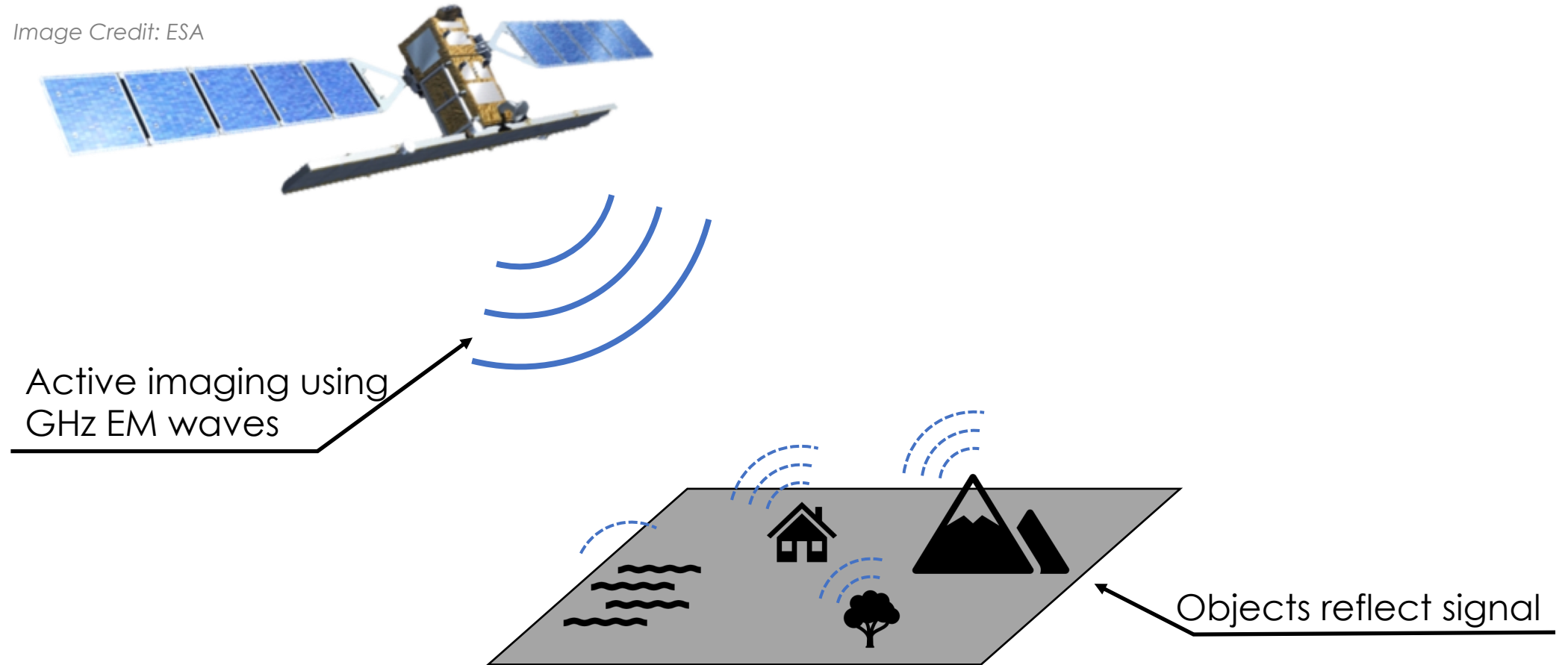
Iran-Iraq Earthquake – Mw 7.3, November 2017



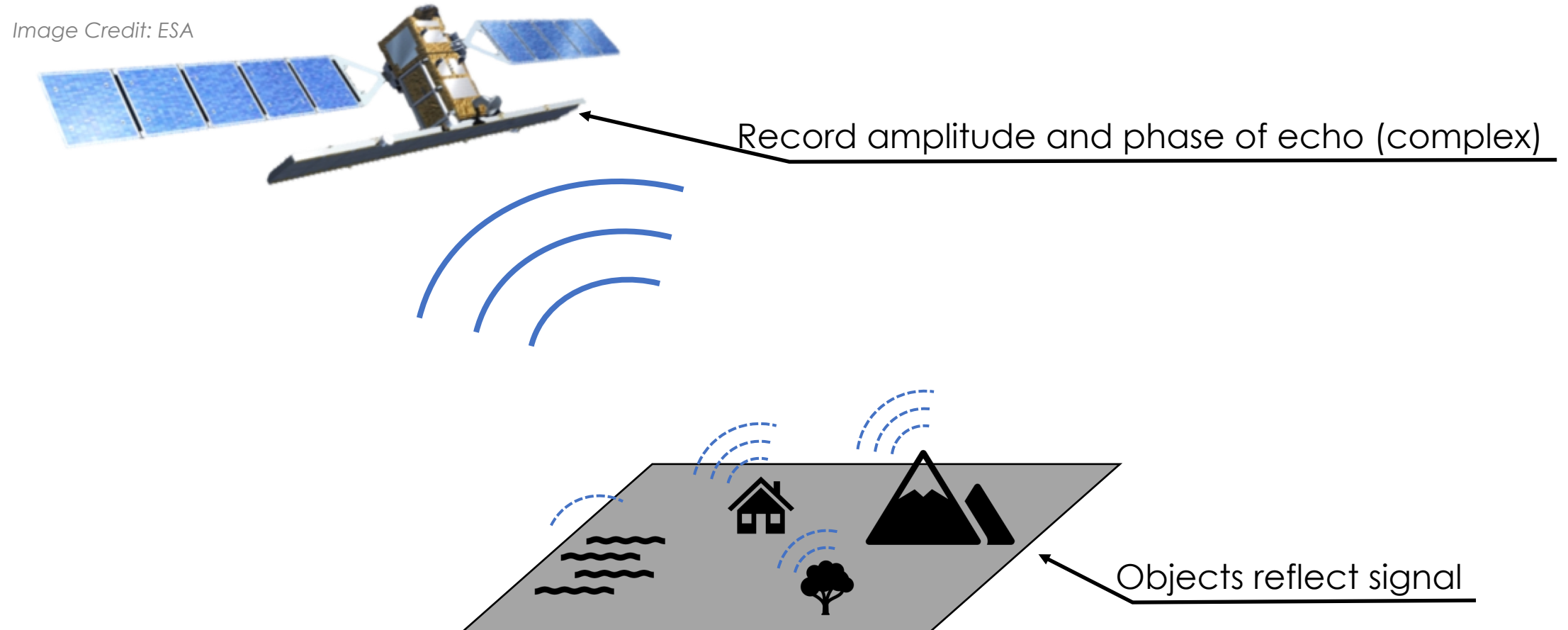
Synthetic Aperture Radar (SAR)



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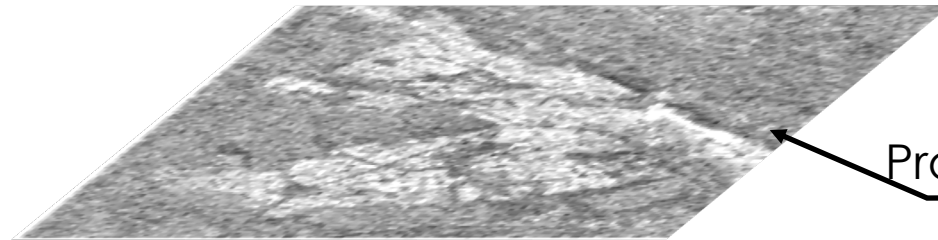
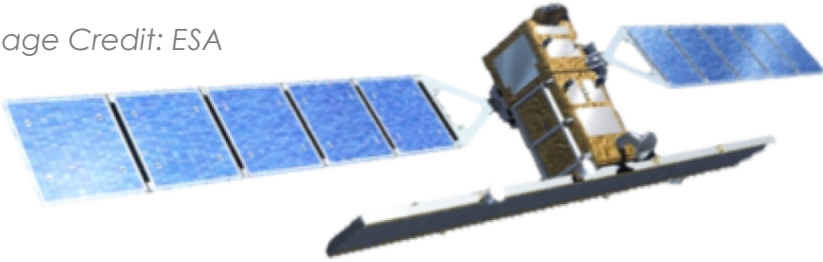


Synthetic Aperture Radar (SAR)



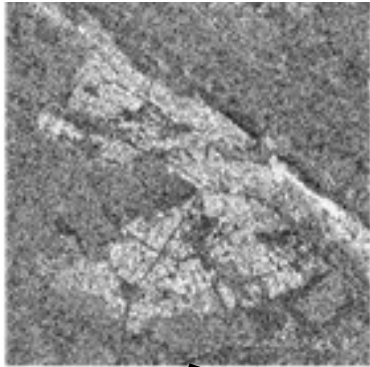
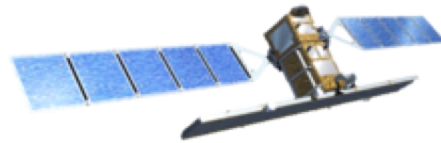
Synthetic Aperture Radar (SAR)

Image Credit: ESA

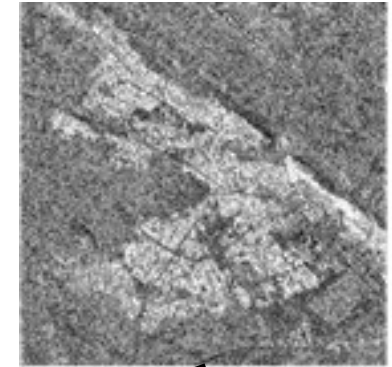
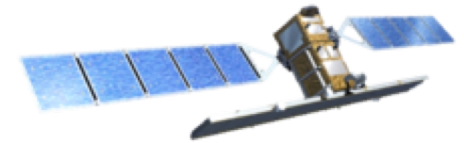


Process to get SAR Image

Look at changes between two SAR images: Interferometric Synthetic Aperture Radar (InSAR)

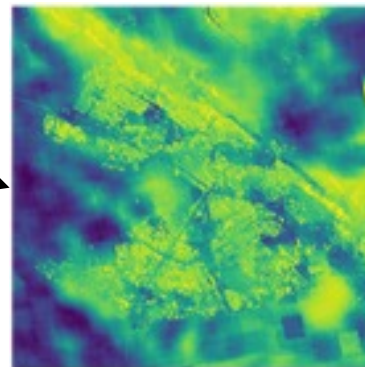


1st SAR image



2nd SAR image

InSAR Coherence

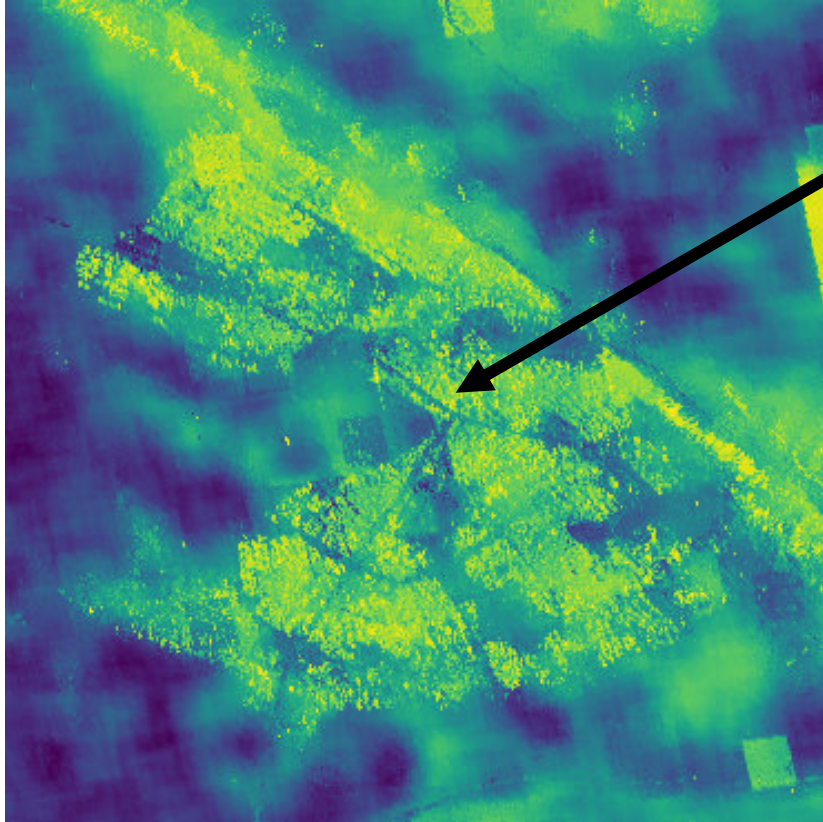


Small changes in the
reflected radar waves
means high coherence

Large changes in the
reflected radar waves
means **low coherence**

InSAR coherence is a measure of surface change

Pre-earthquake

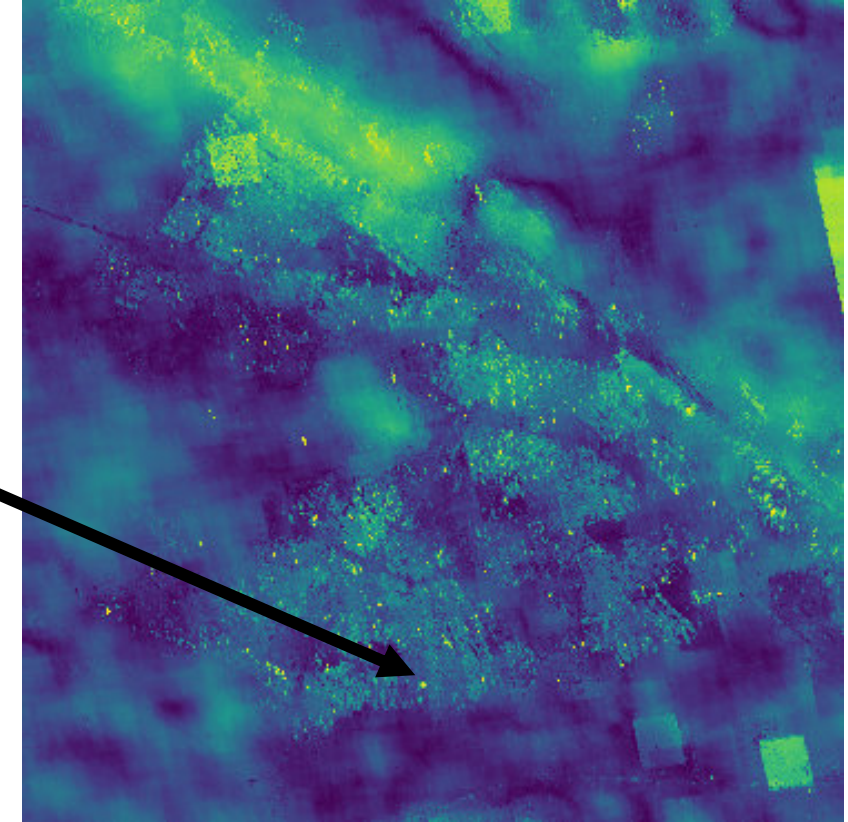


Buildings are stable and reflect radar waves in the same way each time: **high coherence**

If the buildings collapse however, the radar reflection changes: **low coherence**

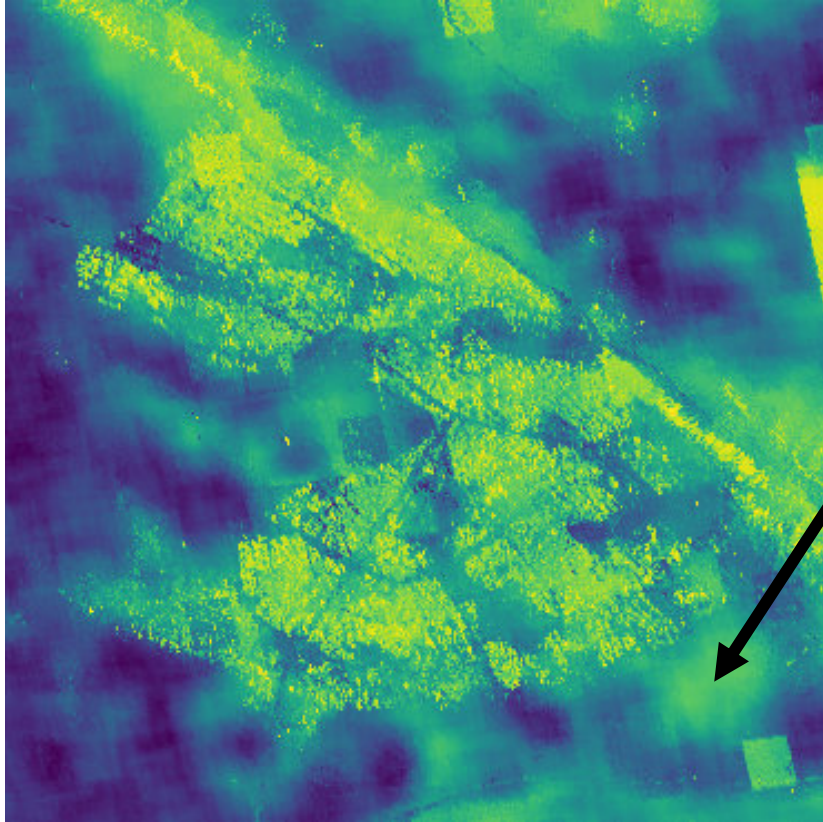


Spanning earthquake

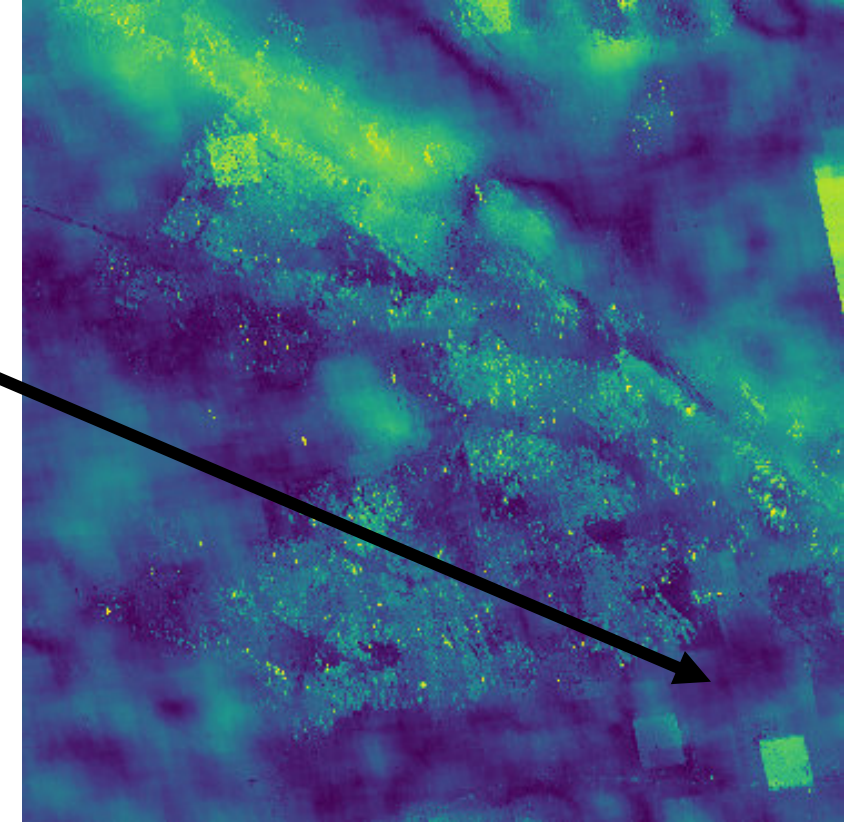


InSAR coherence is a measure of surface change

Pre-earthquake



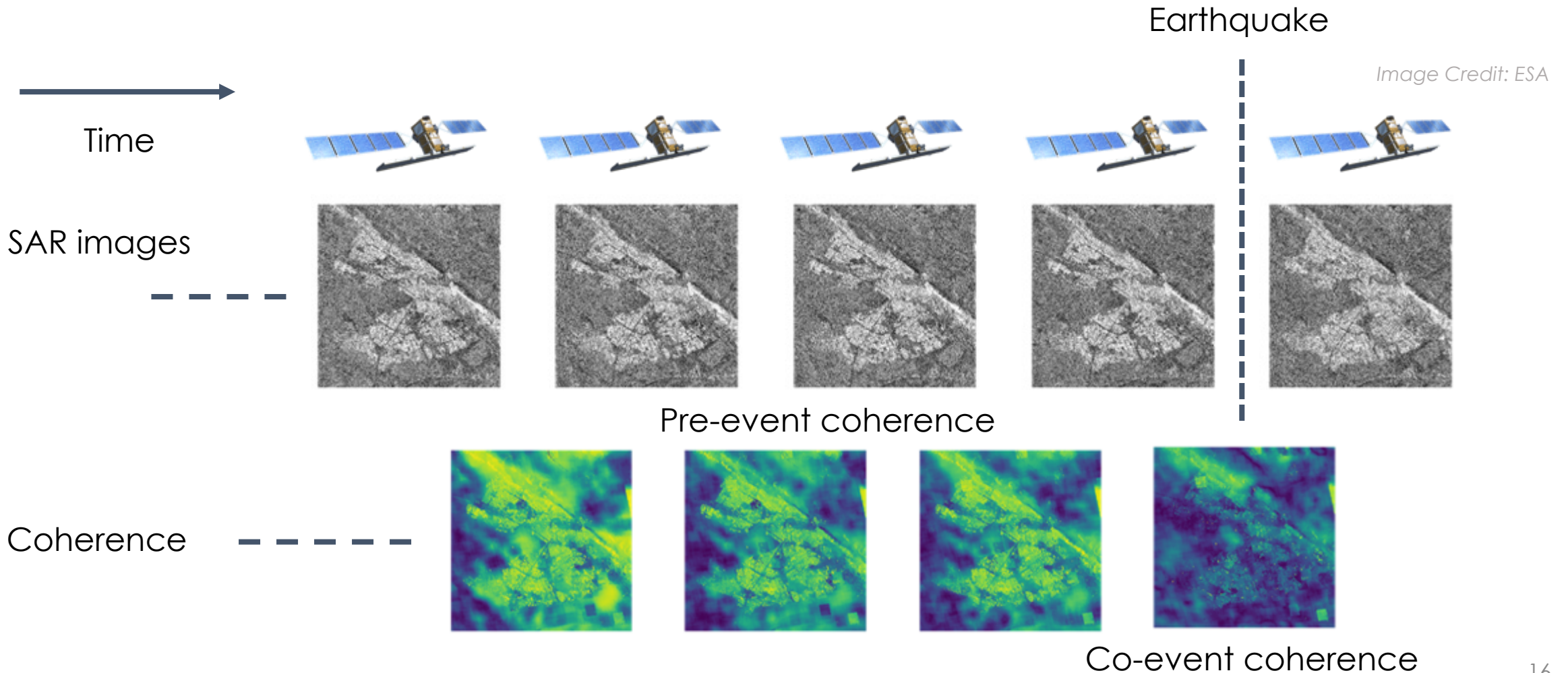
Spanning earthquake



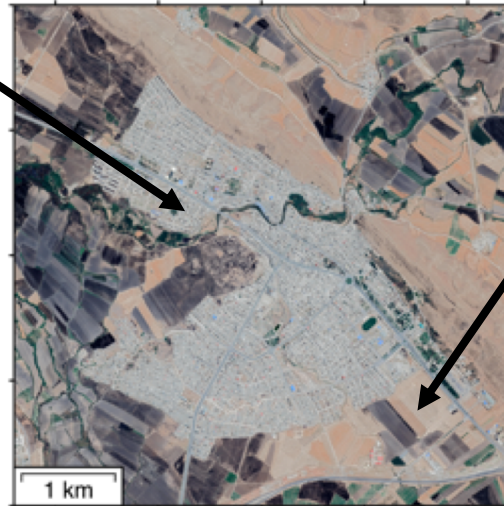
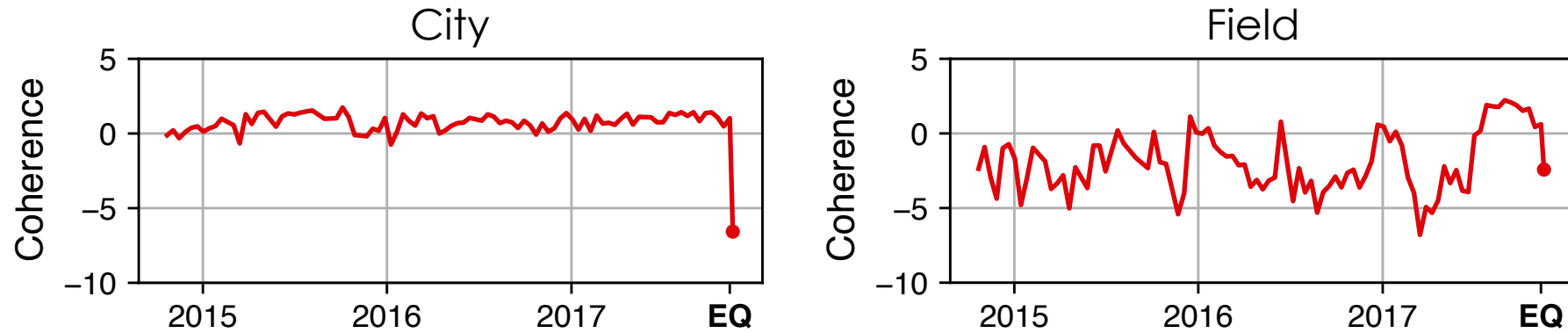
Some areas have very
variable coherence



We can get more information from sequential coherence

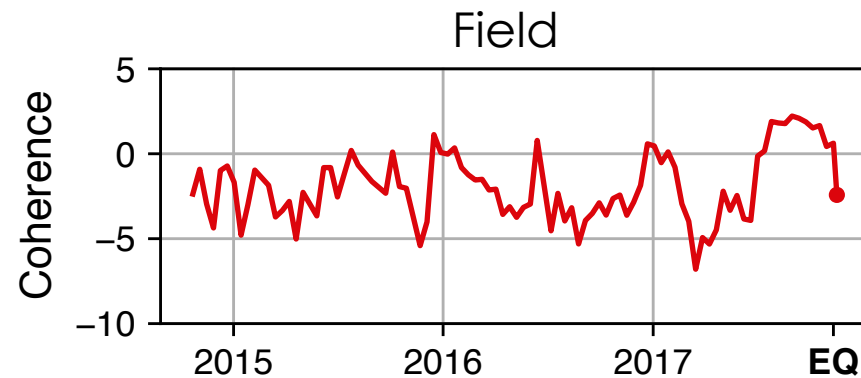
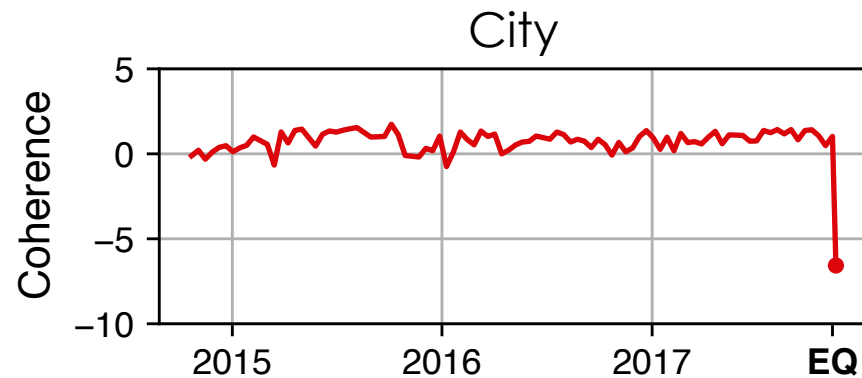


Each pixel has a coherence time series

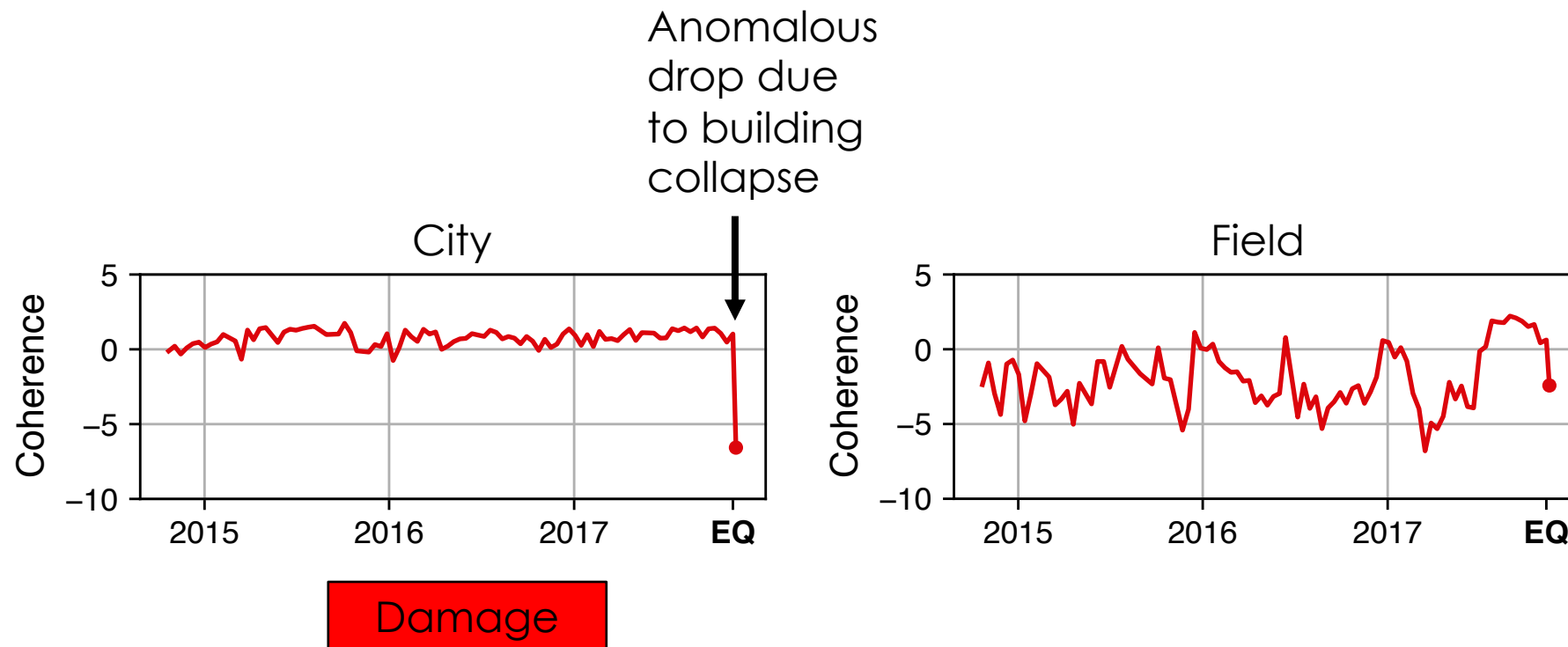


Optical data:
Google/CNES/Airbus

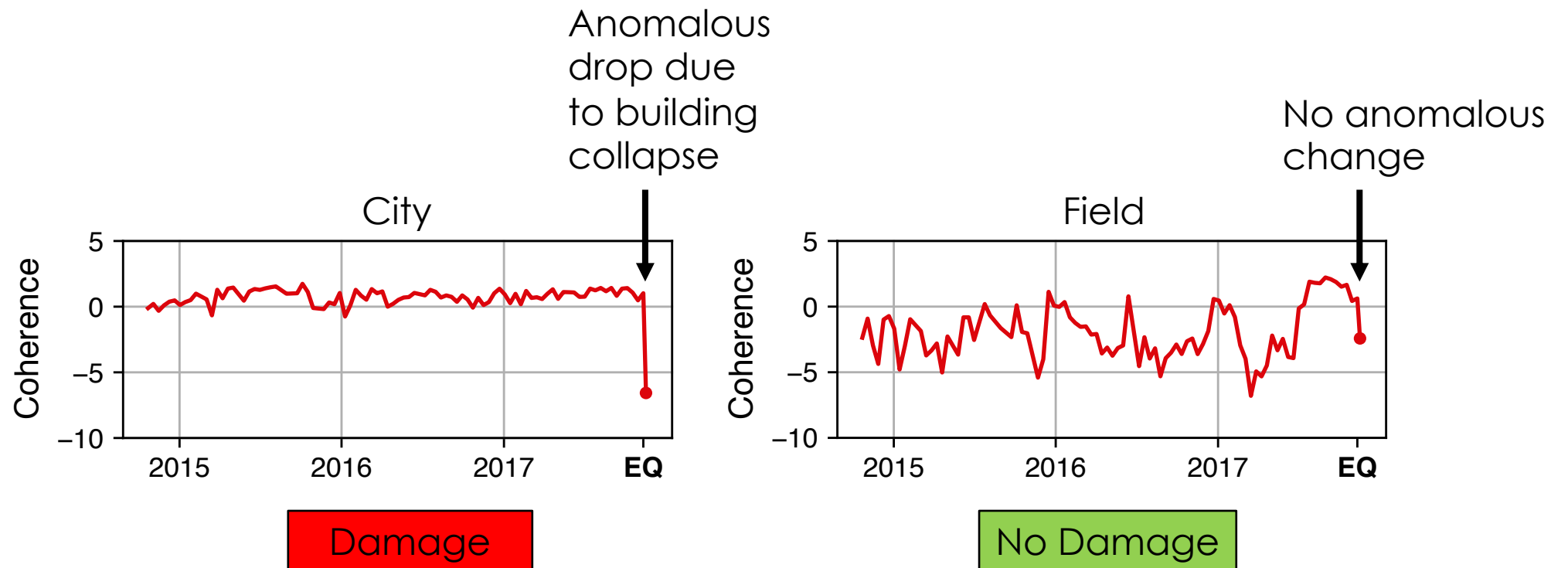
How can we reliably detect anomalies in coherence time series?



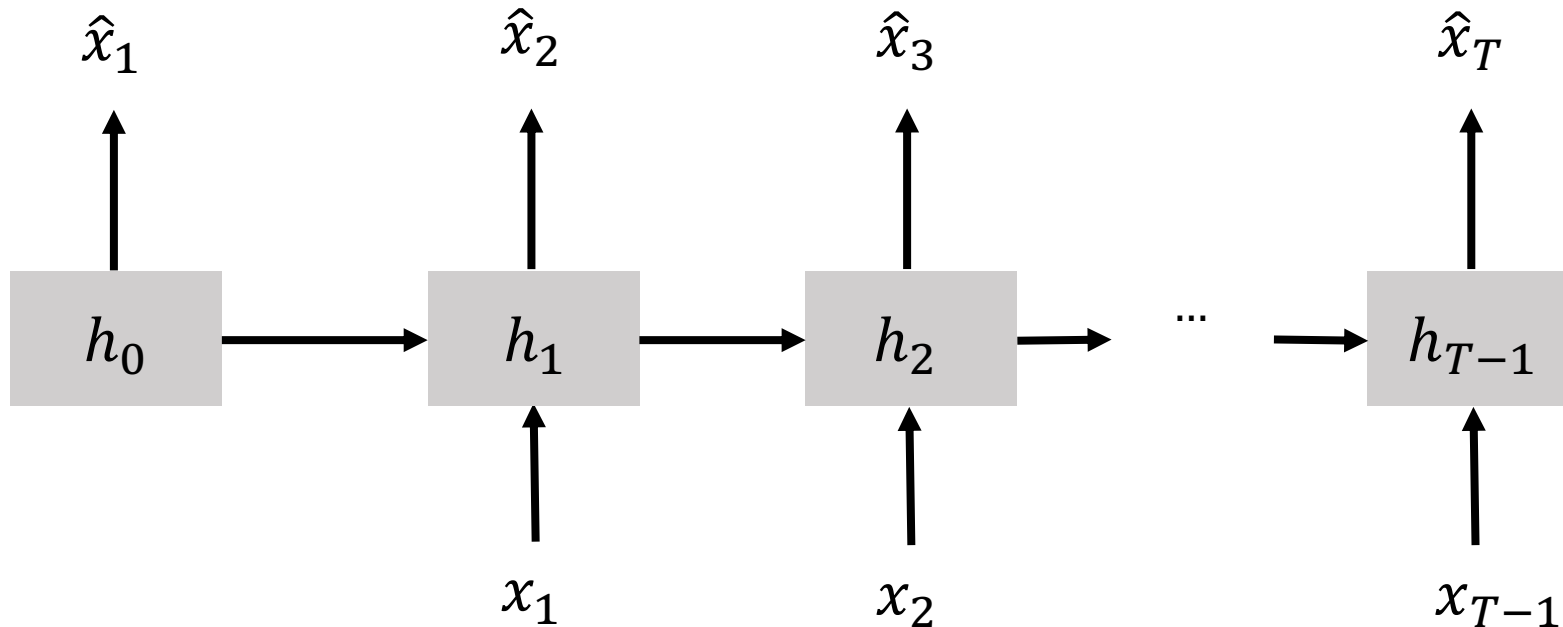
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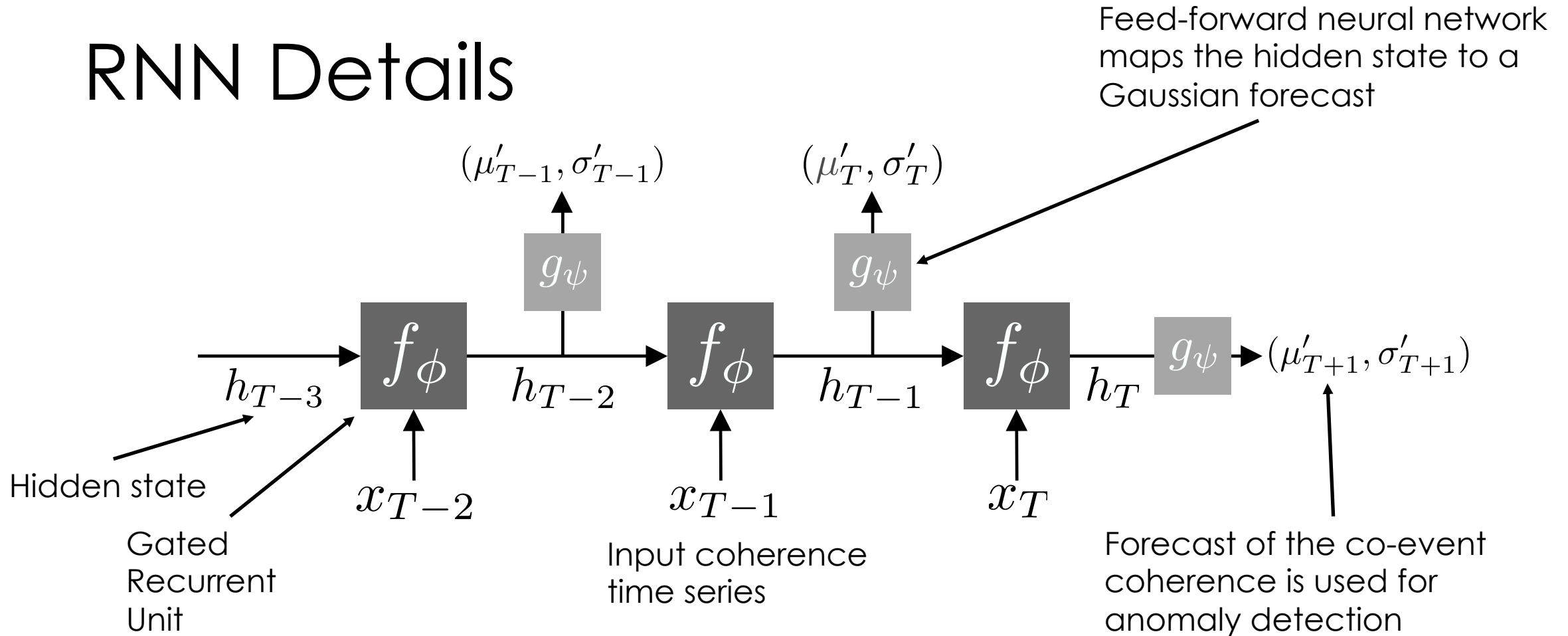


We can use Recurrent Neural Networks (RNNs) for anomaly detection



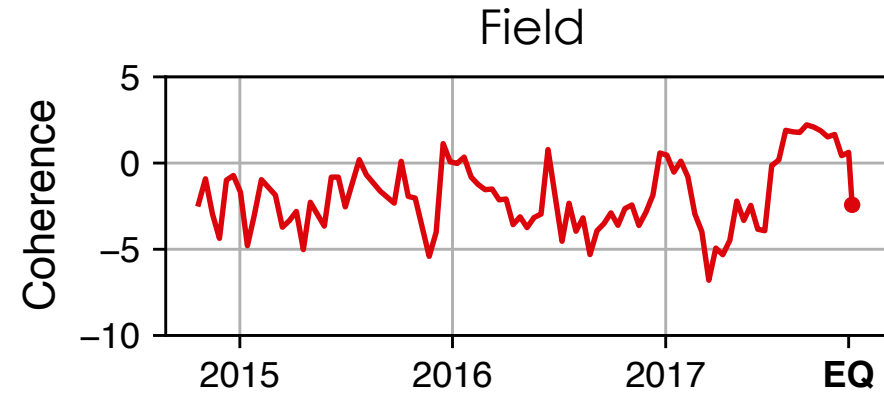
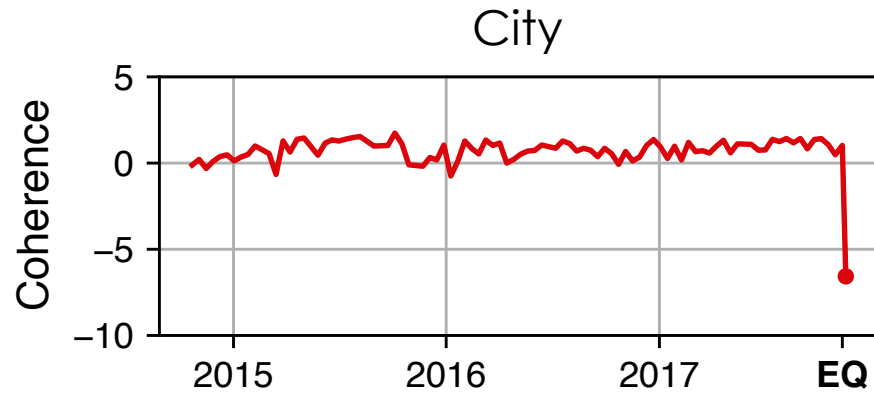
- Input sequence $\{x_1, x_2, \dots, x_T\}$
- Hidden state h_t summarizes the sequence up to time t
- Compute h_t from x_t and h_{t-1} , then predict x_{t+1} from h_t
- Train on many time series to make the 'best' prediction

RNN Details



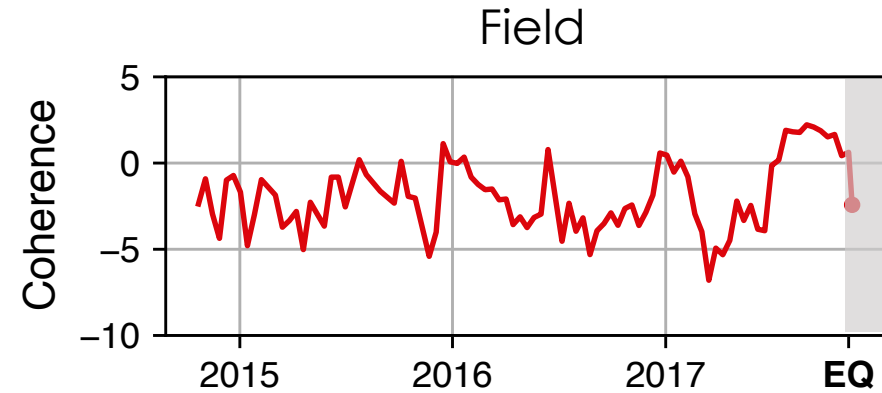
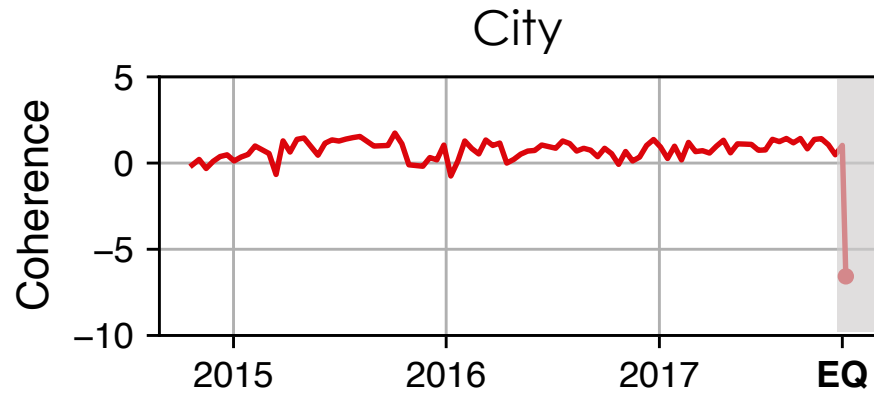
- Total of ~250,000 trainable parameters

Train an RNN on many pre-event coherence time series



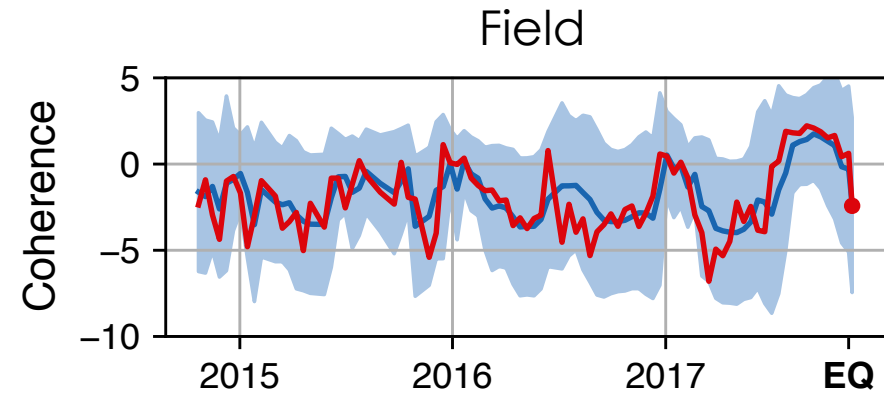
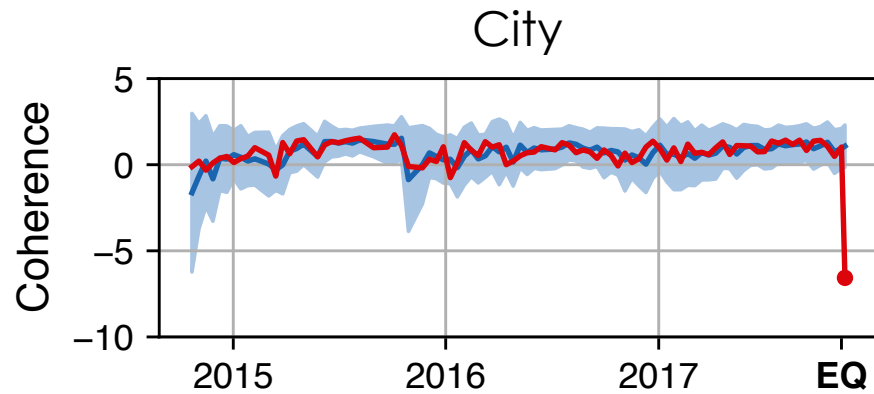
Train on ~3,000,000 coherence time series from the geographic region in which we're doing damage detection

Train an RNN on many pre-event coherence time series



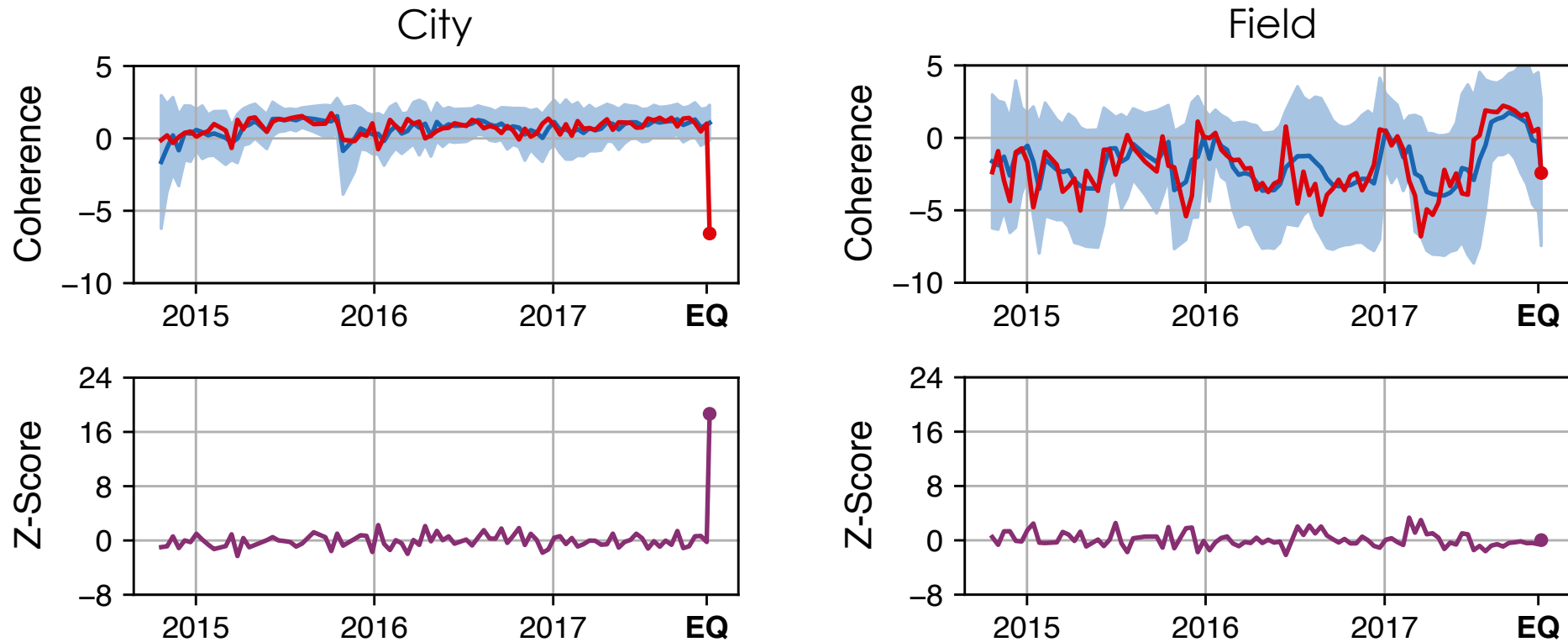
Exclude the co-event coherence during training. We don't want to train on the anomaly!

Use the trained RNN to forecast the co-event coherence



At each step, make
a Gaussian forecast
for the coherence

Compute the deviation from the forecast to detect anomalies



Use the co-event z-score as a proxy for damage

$$z = \frac{\mu'_{T+1} - x_{T+1}}{\sigma'_{T+1}}$$

Overall Method Summary

Observe coherence
behavior
pre-event



Train RNN to
forecast normal
coherence

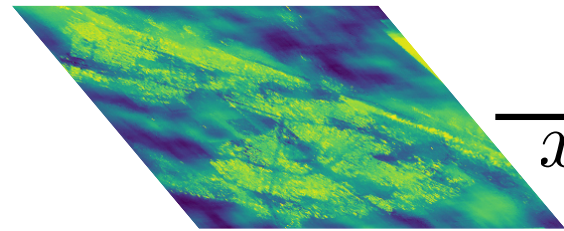


Compare forecast
to observed co-
event coherence

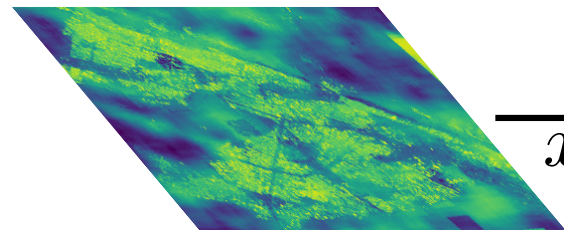


Form damage proxy
map from anomalous
coherence

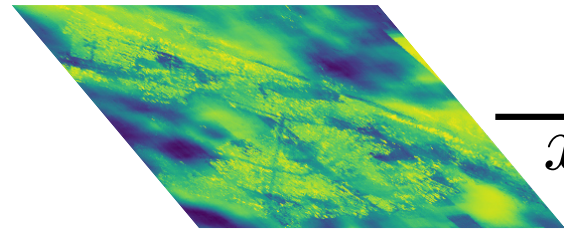
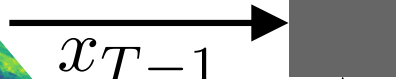
Pre-event coherence



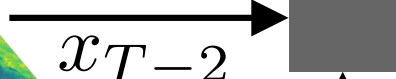
x_T



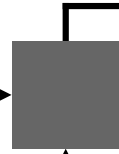
x_{T-1}



x_{T-2}

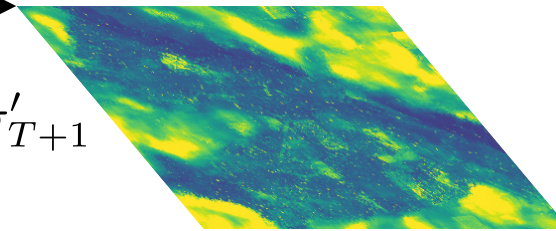


⋮

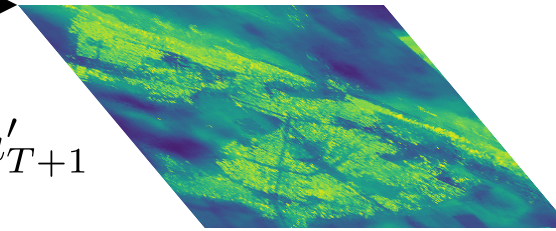


RNN Forecast coherence

σ'_{T+1}

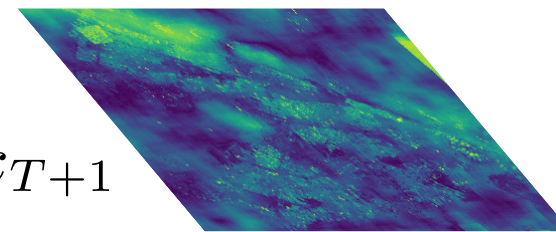


μ'_{T+1}

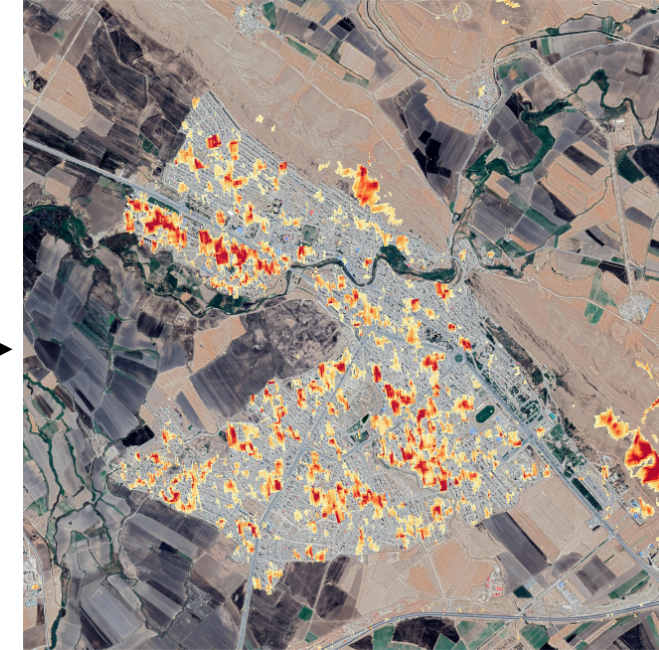


Co-event coherence

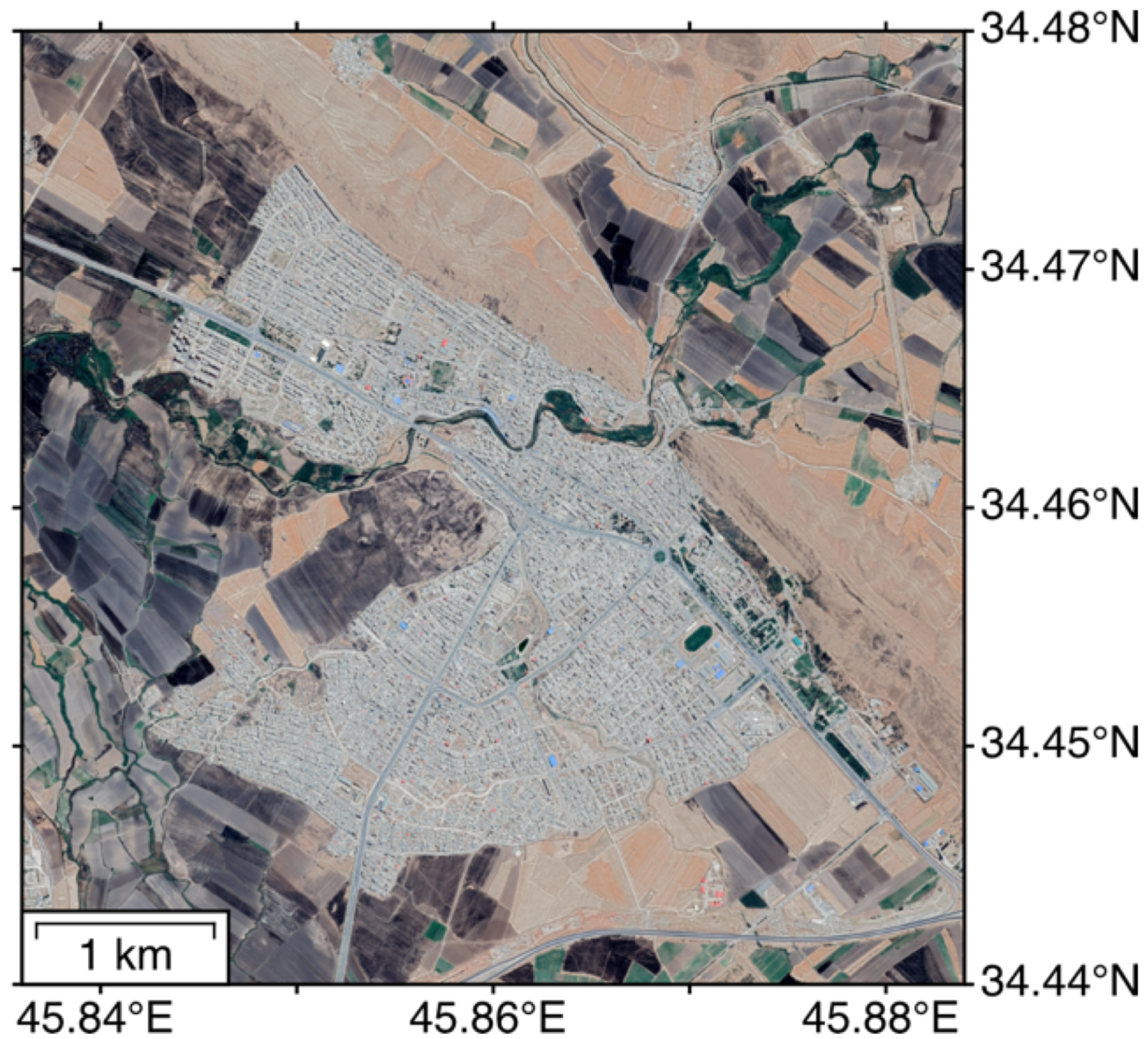
x_{T+1}



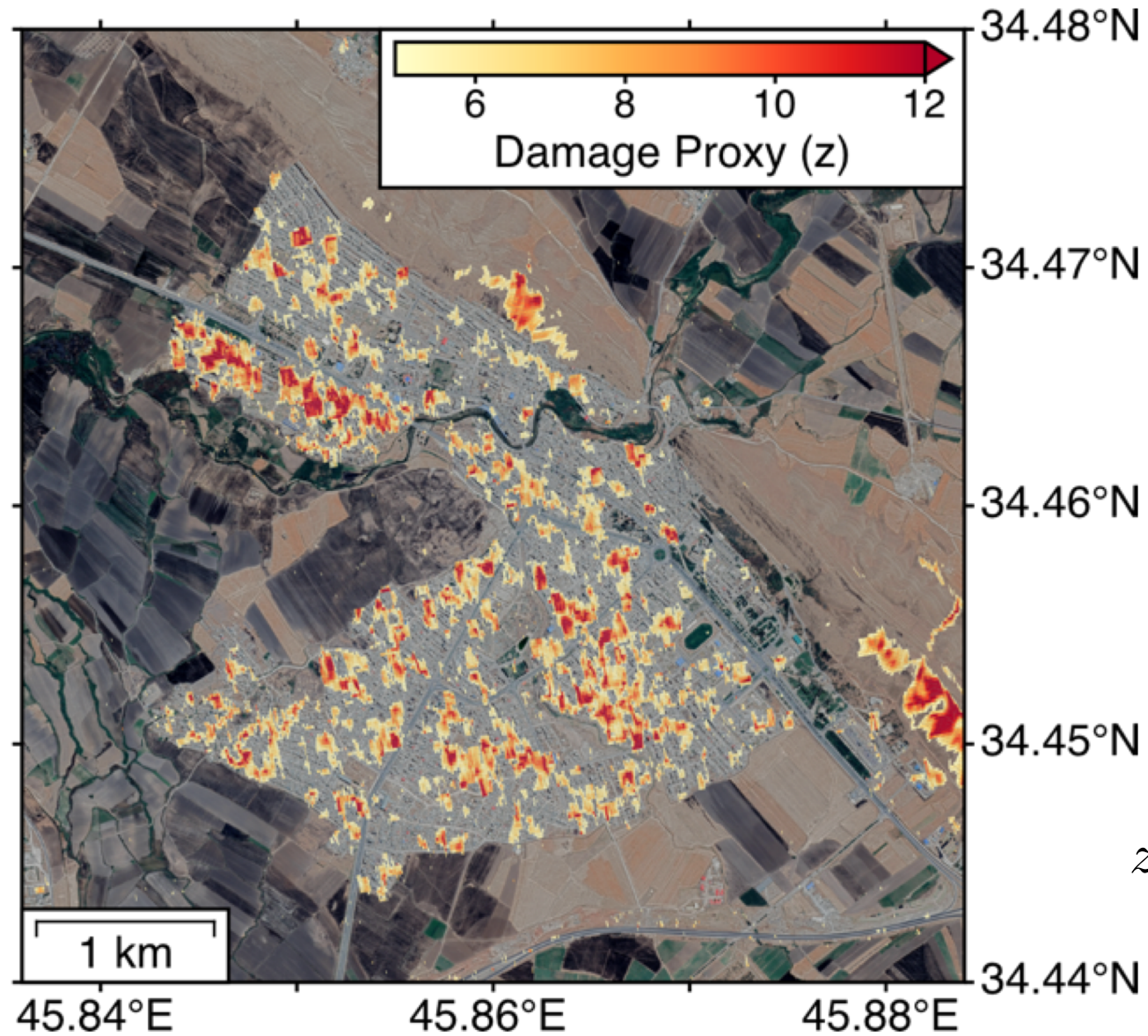
Damage proxy map



$$z = \frac{\mu'_{T+1} - x_{T+1}}{\sigma'_{T+1}}$$



Optical data:
Google/CNES/Airbus



$$z = \frac{\mu'_{T+1} - x_{T+1}}{\sigma'_{T+1}}$$

Optical data:
Google/CNES/Airbus

The 2019 Ridgecrest Earthquakes

Google Earth

Image IBCAO

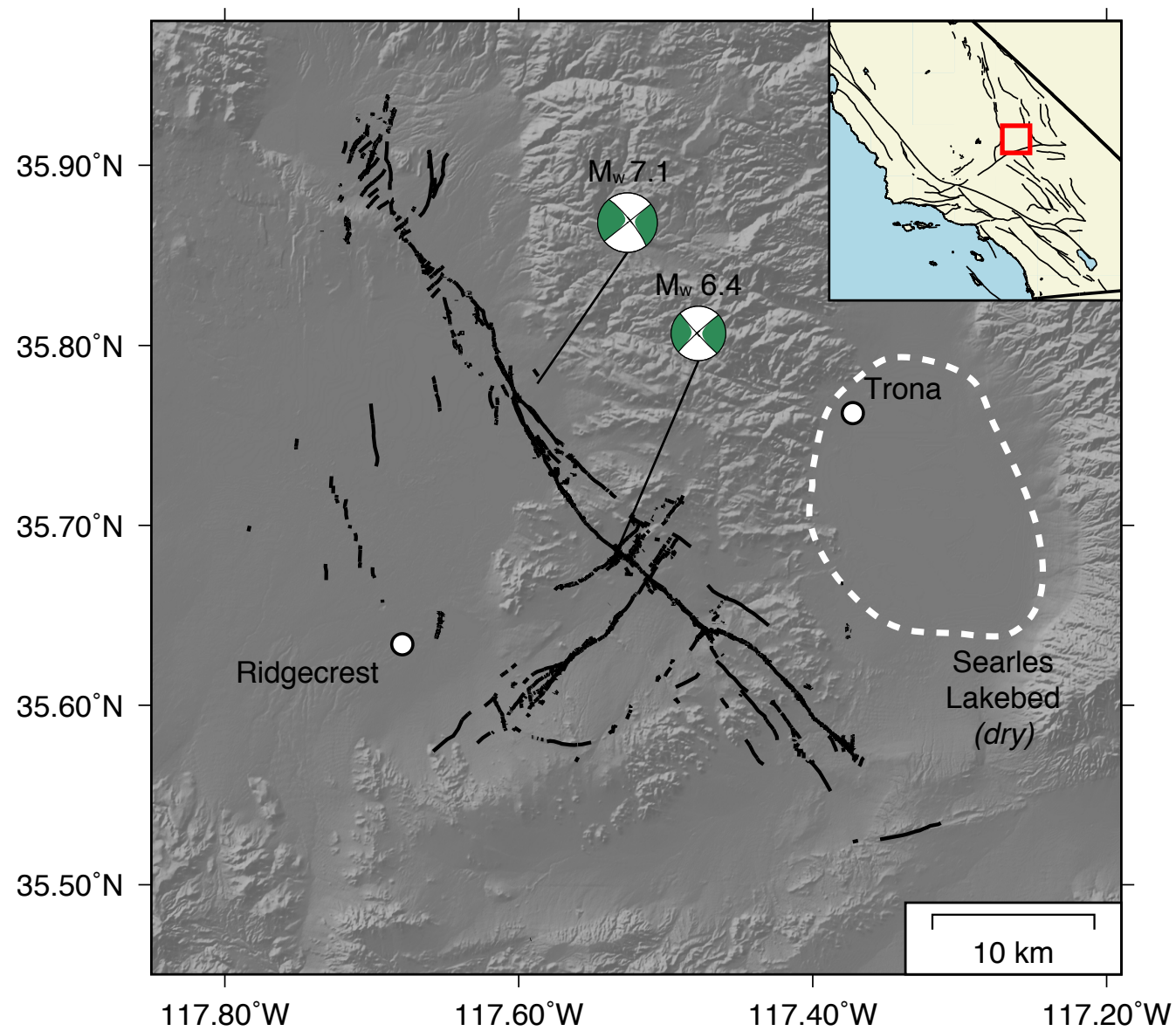
Data LDEO-Columbia, NSF, NOAA

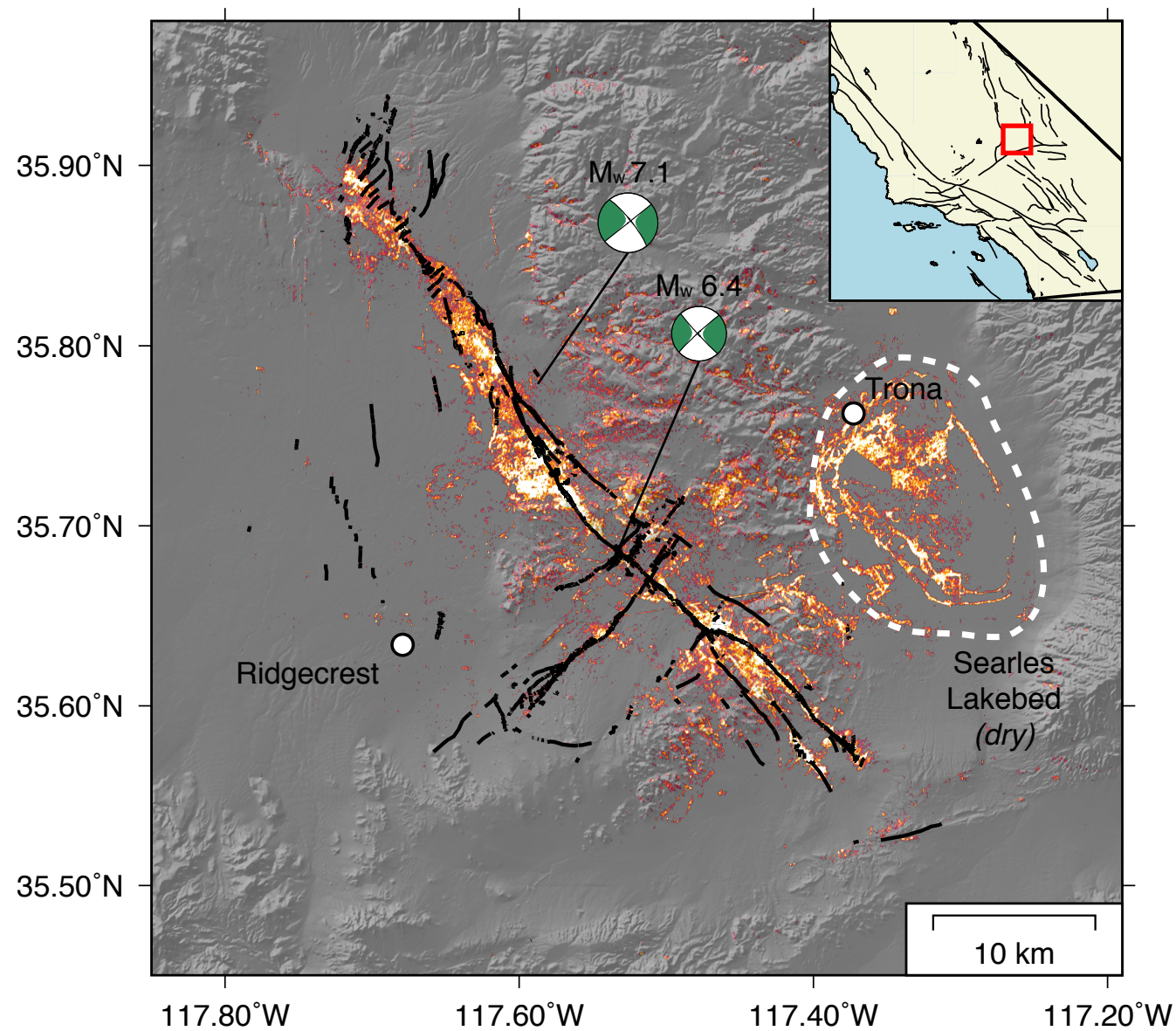
Image Landsat / Copernicus

Data SIO, NOAA, U.S. Navy, NGA, GEBCO

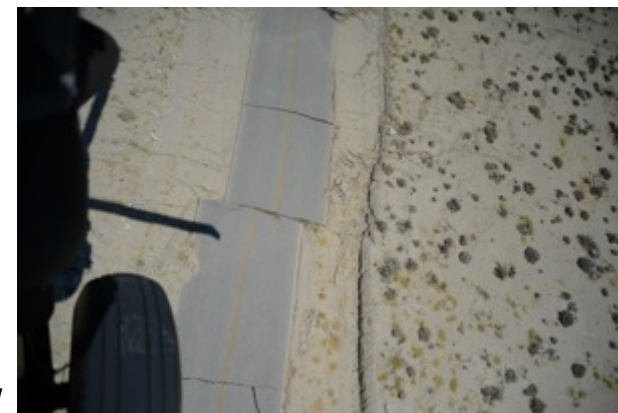
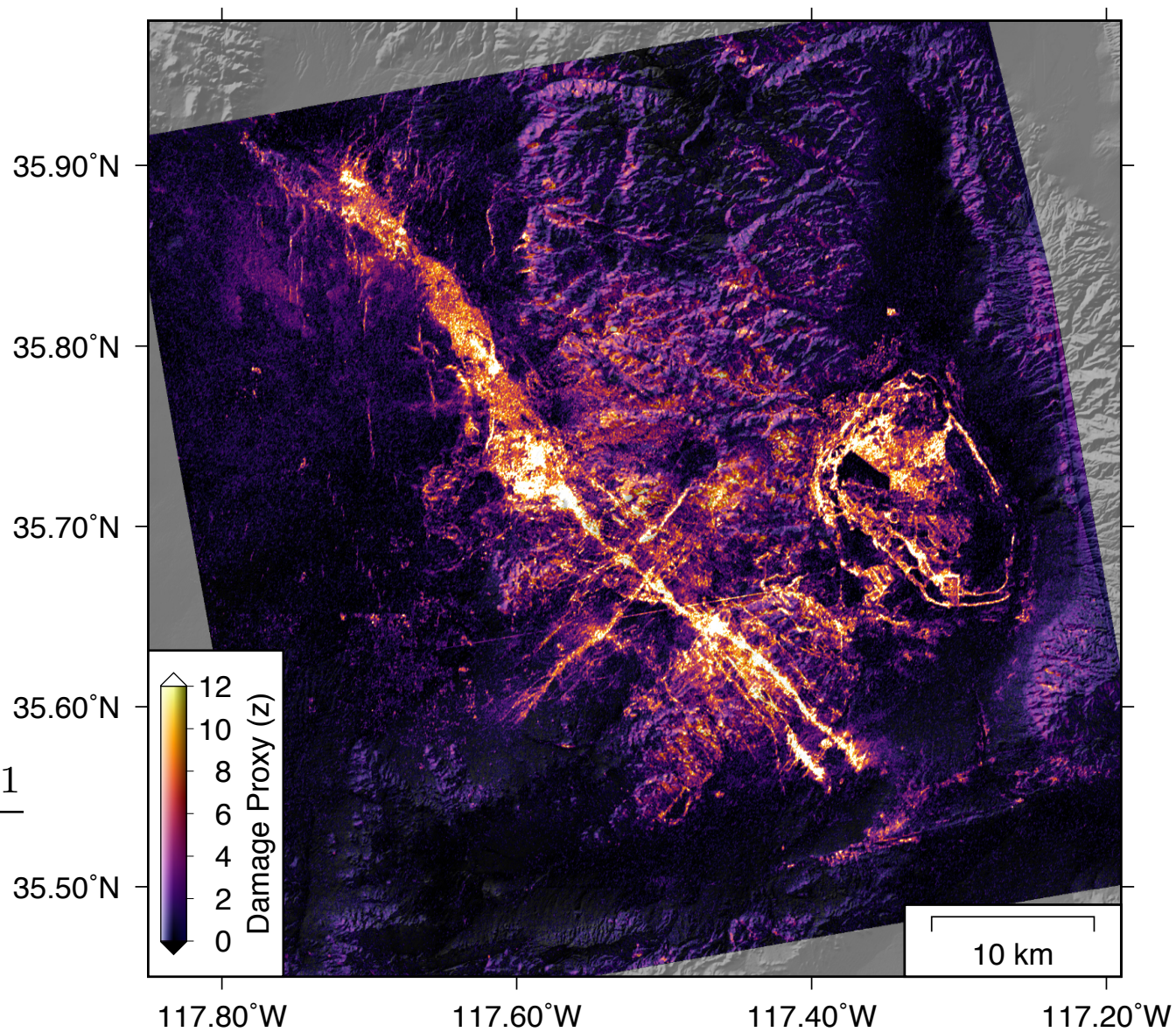


View from Space (Altitude: 4192 mi)





$$z = \frac{\mu'_{T+1} - x_{T+1}}{\sigma'_{T+1}}$$



Photos: USGS

Key Points

1. Synthetic aperture radar (SAR) can see through clouds, day and night, and data is becoming increasingly available
2. We can frame the damage mapping problem as one of [detecting anomalies](#) in [sequential SAR observations](#) of the ground
3. Our approach uses [Recurrent Neural Networks](#) to [forecast the co-event coherence](#) and compare with observations
4. These damage maps can be used to [direct emergency response](#)